

Abstract Solvers for Quantified Boolean Formulas and Their Applications

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Issue

- Usually solving procedures are presented by means of pseudo-code descriptions, but
- some communities have experienced that analyzing such procedures on this basis may not be fruitful.

Instead ...

- more formal descriptions, based on mathematically precise but possibly simple objects, can be useful, and
- can allow for, e.g. a uniform representation.

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Abstract solvers are a relatively new methodology for **analyzing**, **comparing** and **composing** solving procedures in an abstract way via graphs, where

- the states of computation are represented as nodes,
- the solving techniques as arcs between such nodes,
- the solving process as a path in the graph, and
- formal properties of the procedures are reduced to related graph's properties.

DPLL SAT solving: Transition rules of the graph $DPLL_F$

Conclude : $L \implies UNSAT$ if $\left\{ \begin{array}{l} L \text{ is inconsistent and} \\ L \text{ contains no decision literals} \end{array} \right.$

Backtrack : $L \wedge L' \implies L\bar{l}$ if $\left\{ \begin{array}{l} L \wedge L' \text{ is inconsistent and} \\ L' \text{ contains no decision literals} \end{array} \right.$

Unit : $L \implies L \vee l$ if $\left\{ \begin{array}{l} l \text{ does not occur in } L \text{ and} \\ F \text{ contains a clause } C \vee l \text{ and} \\ \text{all the literals of } \bar{C} \text{ occur in } L \end{array} \right.$

Decide : $L \implies L \wedge l$ if $\left\{ \begin{array}{l} L \text{ is consistent and} \\ \text{neither } l \text{ nor } \bar{l} \text{ occur in } L \end{array} \right.$

Success : $L \implies SAT$ if no other rule applies

DPLL SAT solving: Examples

Initial state :	\emptyset	Initial state :	\emptyset
<i>Decide</i>	$\implies a^\Delta$	<i>Decide</i>	$\implies a^\Delta$
<i>Unit</i>	$\implies a^\Delta c$	<i>Decide</i>	$\implies a^\Delta \bar{c}^\Delta$
<i>Decide</i>	$\implies a^\Delta c b^\Delta$	<i>Unit</i>	$\implies a^\Delta \bar{c}^\Delta c$
<i>Success</i>	$\implies SAT$	<i>Backtrack</i>	$\implies a^\Delta c$
		<i>Decide</i>	$\implies a^\Delta c b^\Delta$
		<i>Success</i>	$\implies SAT$

Figure : Examples of paths in $DPLL_{\{a \vee b, \bar{a} \vee c\}}$.

Theorem

For any CNF formula F ,

- 1 graph $DPLL_F$ is finite and acyclic,
- 2 any terminal state reachable from \emptyset in $DPLL_F$ other than UNSAT is SAT, and
- 3 UNSAT is reachable from \emptyset in $DPLL_F$ if and only if F is unsatisfiable.

QBF is the prototypical PSPACE-complete problem.

- In this paper, three abstract solvers for solving QBFs are presented.
- One proposal abstracts the Q-DPLL algorithm for QBF.
- Q-DPLL is an extension of the DPLL algorithm for SAT.

We are given a (prenex CNF) QBF formula F .

QBF $_F$ graph

- The nodes are the states defined similarly as for DPLL, but decision literals are either *universal* (I^{\forall}) or *existential* (I^{\exists}).
- The edges corresponds to updated and additional transition rules wrt DPLL graph.

Q-DPLL for QBFs: Transition rules

<i>Conclude</i>	L	$\implies UNSAT$	if { L is inconsistent and existential free
<i>Backtrack\exists</i>	$L \overset{\exists}{I} L'$	$\implies \bar{L}$	if { $L \overset{\exists}{I} L'$ is inconsistent and $\overset{\exists}{I}$ is the rightmost existential literal
<i>Backtrack\forall</i>	$L \overset{\forall}{I} L'$	$\implies \bar{L}$	if { no other rule applies except <i>Succeed</i> and $\overset{\forall}{I}$ is the rightmost universal literal
<i>Unit</i>	L	$\implies LI$	if { I does not occur in L and for some clause C in the formula, I occurs in C and each other unassigned literal of C is universal and each assigned literal of C is contradicted
<i>Monotone1</i>	L	$\implies LI$	if { the variable of I is existential and I occurs in some clause C and \bar{I} does not occur in any clause C
<i>Monotone2</i>	L	$\implies LI$	if { the variable of I is universal and \bar{I} occurs in some clause C and I does not occur in any clause C
<i>Decide</i>	L	$\implies LI^Q$	if { L is consistent and the variable of I is unassigned and the quantifier of the variable of I is Q and for all I' such that $level(I') < level(I)$ the variable of I' is assigned.
<i>Succeed</i>	L	$\implies Valid$	if { no other rule applies

Figure : The transition rules of the QBF_F graph.

Q-DPLL for QBFs: Example

$$F := \exists a \forall d \exists b c \{ \{ \bar{a}, \bar{d}, b \}, \{ \bar{d}, \bar{b} \}, \{ b, c \}, \{ a, \bar{d}, \bar{c} \}, \{ d, b, \bar{c} \} \} \quad (1)$$

Example

A possible path in QBF_F is:

Initial state :	\emptyset		
Decide	\implies	\bar{a}^{\exists}	Backtrack $_{\exists}$ \implies a
Decide	\implies	$\bar{a}^{\exists} \bar{d}^{\forall}$	Decide \implies $a \bar{d}^{\forall}$
Monotone1	\implies	$\bar{a}^{\exists} \bar{d}^{\forall} b$	Monotone1 \implies $a \bar{d}^{\forall} b$
Backtrack $_{\forall}$	\implies	$\bar{a}^{\exists} \bar{d}$	Backtrack $_{\forall}$ \implies $a \bar{d}$
Unit	\implies	$\bar{a}^{\exists} \bar{d} \bar{c}$	Unit \implies $a \bar{d} b$
Unit	\implies	$\bar{a}^{\exists} \bar{d} \bar{c} \bar{b}$	Fail \implies UNSAT

Q-DPLL for QBFs: Formal result

For any QBF formula F ,

- 1 the graph QBF_F is finite and acyclic;
- 2 Any terminal state in QBF_F is either *UNSAT* or *Valid*;
- 3 If a state *Valid* is reachable from the initial state in QBF_F then F is satisfiable;
- 4 *UNSAT* is reachable from the initial state in QBF_F if and only if F is not satisfiable.